

# Polygon Fills as well as Vertex and Pixel Arrays

CS116A

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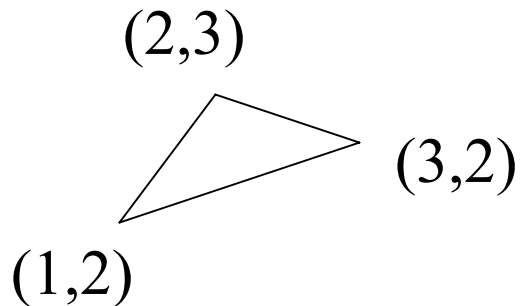
# Introduction

Today we're going to talk about

- Fill Areas
  - Types of Polygons
  - Splitting Concave Polygons
  - Splitting Convex Polygons into Triangles
  - Inside-Outside Tests
  - Polygon Tables
  - Plane Equations
  - Front and Back Faces
  - OpenGL
- Vertex Arrays
- Pixel Arrays

# Types of Polygons

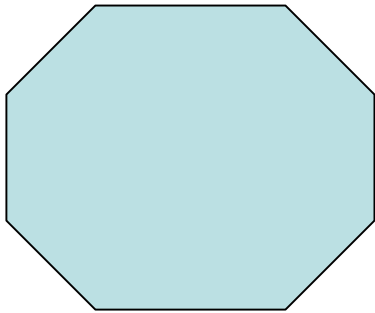
- Polygons are sequences of three or more non-collinear vertices in the plane. Ex.  $((1,2), (2,3), (3,2))$



- Notice join last point back to first. Usually require edges to have at most vertices in common

# Polygon Classifications

- Look at interior angle formed by adjacent edges. If this angle is always less than 180 then polygon called *convex*, otherwise *concave*.



Convex

Concave

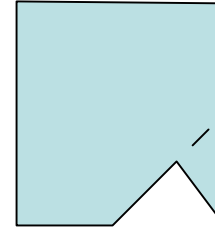


# Identifying Concave Polygons

- Fill algorithms for convex regions easier, so would like an easy algorithm for identifying concave regions.
- If region is convex then the cross-product of adjacent edges will always be of the same sign.
- Make sure to use edges not vertices.  $E_k$  given by  $V_{k+1} - V_k$ .

# Splitting Concave Polygons

## Example



$$E_1 = (1, 0, 0) \quad E_2 = (1, 1, 0)$$

$$E_3 = (1, -1, 0) \quad E_4 = (0, 2, 0)$$

$$E_5 = (-3, 0, 0) \quad E_6 = (0, -2, 0)$$

$$E_1 \times E_2 = (0, 0, 1) \quad E_2 \times E_3 = (0, 0, -2)$$

$$E_3 \times E_4 = (0, 0, 2) \quad E_4 \times E_5 = (0, 0, 6)$$

$$E_5 \times E_6 = (0, 0, 6) \quad E_6 \times E_1 = (0, 0, 2)$$

Since  $E_2 \times E_3$  is negative, split the polygon along the line of vector  $E_2$ . Use line equation to figure where intersect other polygon edge to split polygon into two pieces

# Splitting Convex Polygons into Triangles

- Since triangles are sometimes easier to draw could then split convex polygon into triangles. To do this make any sequence of three consecutive vertices a new triangle. Then delete the middle vertex from the original list of vertices.

# Inside-Outside Tests

- To do filling often want to know what is the inside and what is the outside region of a figure.
- **Odd-Even rule:** let  $(x,y)$  be the point we are trying to determine if it is inside or outside of an object. Draw a line between this point and a distant point  $P$ . If the number of edges of the polyline it crosses is odd then it is an interior point.
- **Nonzero Winding Number Rule:** Draw a line between a  $(x,y)$  and  $P$ . Now add sum of signs of cross-products of this line with the lines it crosses. If sum is nonzero then is an interior point.



# Polygons Tables

- Typically polygons are used in rendering 3D objects. To do this it is convenient to arrange data into three tables: A list of vertices. A list of edges specified as pairs of elements from the first list. A list of polygons specified as sequence of elements from the edge list.

# Plane Equations

- In a 3D scene each polygon will live in some plane. So useful to know a little about planes.

General equation is:

$$Ax + By + Cz + D = 0$$

- Can write as:  $(A/D)x + (B/D)y + (C/D)z = -1$
- Let  $A' = (A/D)$ , define  $B'$  and  $C'$  similarly. Then given three points can solve for these values.
- A normal to the plane is the vector  $(A, B, C)$

# Front and Back Faces

- The side of a polygon that faces into the interior of a 3D object called a *back face*. Other side called *front face*.
- Given a polygon, let  $Ax+By+Cz+D=0$  be its plane. Then a point  $(x,y,z)$  is behind the plane if for  $Ax+By+Cz+D < 0$ . If  $> 0$  then in front of plane.

# OpenGL

- Can draw rectangles with:

```
int vertex1[] = {200, 100};
```

```
int vertex2[] = {50, 250};
```

```
glRectiv(vertex1, vertex2);
```

- For more general shapes easier to use glBegin, glEnd with one of GL\_POLYGON, GL\_TRIANGLES, GL\_QUADS, GL\_TRIANGLES\_STRIP, GL\_TRIANGLES\_FAN, GL\_QUAD\_STRIP, GL\_QUAD\_FAN

# Vertex Arrays

- Useful to have a way to store list of points that make up an object:

```
typedef GLint vertex3[3];
```

```
vertex3 pt[8] = {{0,0,0},{0,1,0},{1,0,0},{1,1,0},  
{0,0,1},{0,1,1},{1,0,1},{1,1,1}};
```

- Above could be used for a cube.
- To plot faces can make calls beginning with either `glBegin(GL_POLYGON)` or `glBegin(GL_QUADS)`

# Vertex Arrays cont'd

- This would require many OpenGL function calls.
- To alleviate this problem use Vertex Arrays:  

```
glEnableClientState(GL_VERTEX_ARRAY);  
glVertexPointer(3, GL_INT, 0, pt);  
GLubyte vertIndex[] = (6,2,3,7, 5,1,0,4, 7,3,1,5, 4,0,2,6,  
    2,0,1,3, 7,5,4,6);  
glDrawElements(GL_QUADS, 24, GL_UNSIGNED,  
    vertIndex);
```
- Vertex arrays can be disabled with  

```
glDisableClientState(GL_VERTEX_ARRAY);
```

# Pixel Arrays

- Pixmaps -- rectangular arrays of colour values.
- If only have colour-depth 1 then called a *bitmap*.
- In OpenGL can draw this using:

```
glBitmap(width, height, x0, y0, xOffset, yOffset,  
        bitShape); //for bitmaps  
  
glDrawPixels(width, height, dataFormat, dataType,  
            pixMap); // for pixmaps
```
- Note data format can be things like `GL_RGB`.  
Datatype might be `GL_INT`

# More Pixel Arrays

Example code fragment:

```
GLubyte bitShape[20] = {  
    0x1c, 0x00, 0x1c, 0x00, 0x1c, 0x00, 0x1c, 0x00,  
    0x1c, 0x00,  
    0xff, 0x80, 0x7f, 0x00, 0x 3e, 0x00, 0x1c, 0x00,  
    0x08, 0x00};  
glPixelStorei(GL_UNPACK_ALIGNMENT,1);  
glRasterPos2i(30,40);  
glBitmap(9, 10, 0.0, 0.0, 20.0, 15.0, bitShape);
```



# More on Pixmaps

- If using a buffer can specify buffer to draw to using  
`glDrawBuffer(buffer); //GL_BACK`
- Can read a group of pixels using  
`glReadPixel(xmin,ynim, width, height,  
dataformat, dataType, array);`
- Can set buffer to read to with  
`glReadBuffer(buffer)`