Neural Collaborative Filtering Recommendation Strategy using Deep Neural Networks

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Introduction

- items.
- to learn the user-item interaction function
- done by many previous work

• This paper strives to develop techniques based on neural networks to tackle the key problems in recommendation collaborative filtering — on the basis of implicit feedback. Although some recent work has employed deep learning for recommendation, they primarily used it to model auxiliary information, such as textual descriptions of items and acoustic features of musics. When it comes to model the key factor in collaborative filtering — the interaction between user and item features, they still resorted to matrix factorization and applied an inner product on the latent features of users and

• By replacing the inner product with a neural architecture that can learn an arbitrary function from data, the paper present a general framework named NCF, short for Neural network- based Collaborative Filtering. NCF is generic and can express and generalize matrix factorization under its frame- work. To supercharge NCF modeling with non-linearities, the paper propose to leverage a multi-layer perceptron

• The inner product, which simply combines the multiplication of latent features linearly, may not be sufficient to capture the complex structure of user interaction data. This paper explores the use of deep neural networks for learning the interaction function from data, rather than a handcraft that has been







Matrix Factorization

- Let M and N denote the number of users and items, respectively. We define the user-item interaction matrix $Y \in R^{M \times N}$ from users' implicit feedback as, $y_{ui} = 1$ - if interaction (user u, item i) is observed; $y_{ui} = 0$, otherwise.
- MF associates each user and item with a real-valued vector of latent features. Let pu and qi denote the latent vector for user u and item i, respectively, MF estimates an interaction y_{ui} as the inner product of p_u and q_i

$$\hat{y}_{ui} = f(u, i \mid p_u,$$



space (b), placing p4 closest to p1 makes p4 closer to p2 than p3, incurring a large ranking loss



An example illustrates MF's limitation. From data matrix (a), u₄ is most similar to u₁, followed by u₃, and lastly u₂. However in the latent

NCF General Framework

and v_i that describe user *u* and item *i*, respectively



Figure 2: Neural collaborative filtering framework

- training is performed by minimizing the point wise loss between y^{A}_{ui} and its target value y_{ui}
- The NCF's predictive model is formulated as

$$\hat{y}_{ui} = f(P^2)$$

• To permit a full neural treatment of collaborative filtering, the paper adopt a multi-layer representation to model a user-item interaction you as shown in figure, where the output of one layer serves as the input of the next one. The bottom input layer consists of two feature vectors v_u

• Above the input layer is the embedding layer, it is a fully connected layer that projects the sparse representation to a dense vector. The obtained user (item) embedding can be seen as the latent vector for user (item) in the context of latent factor model. The user embedding and item embedding are then fed into a multi-layer neural architecture, which we term as neural collaborative filtering layers, to map the latent vectors to prediction scores. Each layer of the neural CF layers can be customized to discover certain latent structures of user-item interactions. The dimension of the last hidden layer X determines the model's capability. The final output layer is the predicted score y^{A}_{ui} , and

 $P^T v_u^U, Q^T v_i^I | P, Q, \theta_f)$



Neural matrix factorization model

• The paper then extends their proposed method to combine MF with multi-layer perceptron as shown under





is given as follows

$$\hat{y}_{ui} = 0$$

- method propose to initialize NeuMF using the pre-trained models of GMF and MLP.
- between the two pre-trained models

Figure 3: Neural matrix factorization model

• The paper allows MF and MLP to learn separate embeddings, and combine the two models by concatenating their last hidden layer, the formulation of which

 $\sigma(h^T[\phi^{MF}\phi^{MLP}])$

• Due to the non-convexity of the objective function of NeuMF, gradient-based optimization methods only find locally-optimal solutions. It is reported that the initialization plays an important role for the convergence and performance of deep learning models. Since NeuMF is an ensemble of GMF and MLP, the

• First train GMF and MLP with random initializations until convergence, then use their model parameters as the initialization for the corresponding parts of NeuMF's parameters. The only tweak is on the output layer, where concatenate weights of the two models with a hyper parameter α determining the trade-off

