

Hierarchy Theorems

CS254

Chris Pollett

Oct 9, 2006.

Outline

- Complexity Classes
- The Hierarchy Theorem
- Relationships Between Classes

Complexity Classes

- Complexity classes are made up of several parameters.
 - Model of computation -- we are using k-tape machines
 - Mode -- we will consider deterministic and nondeterministic modes
 - Resource -- we are mainly interested in the resources of time and space.
 - Bound -- how many units of the given resource we are allowed to use. This is typically given by some function f .

Proper Complexity Functions

- What makes a good function for a resource bound?
 - We want to avoid weird functions like $f(n) = 0$ if n is even and is equal to 2^n if n is odd.

Defⁿ Let f be a function from the nonnegative integers to the nonnegative integers. We say f is a *proper complexity function* if f is nondecreasing and there is a deterministic TM M_f which when started with x on the input tape, runs for $t=O(|x| + f(|x|))$ steps using at most $O(f(|x|))$ space which outputs to an output tape the string $I^{f(|x|)}$. Here space is measured disregarding the input, and output. The input tape is assumed to be read-only and we assume we also have a dedicated, write-only output tape.

- For example, a constant c , n , $\lceil \log n \rceil$ are all proper complexity functions. One can show that if f and g are proper so are $f+g$, $f * g$, and 2^g .

Precise Machines

- One application of proper complexity classes is that we can get our machines to run for the same amount of time on all inputs of the same length.

Defⁿ A Turing machine M is *precise*, if there are functions f and g , such that for every input x of length n and every computation of M on x , M halts after precisely $f(n)$ steps and except for the input and output tape, all other tapes have used length precisely $g(n)$.

Prop. Suppose (deterministic or nondeterministic) M decides L within time (or space) $f(n)$, where f is a proper function. Then there is a precise machine M' , which decides the same language in time (resp. space) $O(f(n))$.

Proof. We will only consider the time case, the space case is similar. First on input x , M' computes the machine M_f for f using a new set of tapes. After this computation ends, M' has $I^{f(|x|)}$ written on some tape. M' rewinds this tape. So far the computation is deterministic. M' then begins simulating M which may be deterministic or nondeterministic. At each step of simulating M , M' advances the tape head on the tape with $I^{f(|x|)}$ written on it. M halts in at most $f(n)$ steps. At which point, M' remembers how M halted and continues down the tape with $I^{f(|x|)}$ on it until it gets to a blank. At this point it halts in the same way as M .

Specific Complexity Classes

- We will be interested in the complexity classes $\text{TIME}(f)$, $\text{SPACE}(f)$, $\text{NTIME}(f)$, and $\text{NSPACE}(f)$ usually for some proper function f .
- We will also be interested in the unions of such classes. For instance,
$$P = \bigcup_{j \geq 0} \text{TIME}(n^j),$$
$$\text{NP} = \bigcup_{j \geq 0} \text{NTIME}(n^j),$$
$$\text{PSPACE} = \bigcup_{j \geq 0} \text{SPACE}(n^j),$$
$$\text{NPSPACE} = \bigcup_{j \geq 0} \text{NPSPACE}(n^j),$$
$$E = \bigcup_{j \geq 0} \text{TIME}(2^{j \cdot n}),$$
$$\text{EXP} = \bigcup_{j \geq 0} \text{TIME}(2^{n^j}),$$
- Finally, we will consider the classes $L = \text{SPACE}(\log n)$ and $\text{NL} = \text{NSPACE}(\log n)$. For these classes, the input tape is read-only and space is measured in terms of squares used on the work tapes.
- Given a class of language C , the class of languages $\text{co-}C$ are defined as $\{\bar{L} \mid L \text{ is in } C\}$. For example, co-r.e. , co-NP , etc.

The Hierarchy Theorem

- We next turn to the question of when can we show a language is in $\text{TIME}(f)$ but not in $\text{TIME}(g)$? Here g is a slower growing proper function than f .
- To do this we are going to look at clocked based variant of the halting problem. For $f(n) \geq n$, define:
$$H_f = \{ \langle M, x \rangle \mid M \text{ accepts input } x \text{ after at most } f(|x|) \text{ steps} \}$$

More on the Hierarchy Theorem

Lemma. $H_f \in \text{TIME}((f(n))^3)$.

Proof. We will give a variation of a universal machine to prove this. Let U_f have 4 tapes.

Let $n = |\langle M, x \rangle|$. First, U_f use M_f to write an “alarm clock” amount of time $I^{f(n)}$ on the fourth tape. The fourth head is then rewound. Using the input $\langle M, x \rangle$, the second tape is initialized to encode the start state s of M , $\langle M \rangle$ is copied to the third tape and converted into a 1-tape machine using our earlier simulation (this machine executes one step of the original machine in at most $O(f(n))$ steps and we could speed this to $f(n)$). The first tape is set up with just x on it. Doing all this, takes $O(f(n))$ time. The modified M is then simulated step by step. This involves:

- Comparing the current state, and current head position of tape 1 against the transition function of M on tape 3 until a match is found
- applying the appropriate change to the first tape and updating the current state on the second tape.
- advancing the alarm clock tape.

Simulating one step of the modified M take $O(f(n))$ steps on U_f . So simulating one step of the original takes $O(f(n)^2)$ steps on U_f . We simulate exactly $f(n)$ steps of M by using our clock and determine if we have accepted by then. So the total time is $O(f(n)^3)$, which gives $H_f \in \text{TIME}((f(n))^3)$. as desired.

Still More on the Hierarchy Theorem

Lemma $H_f \notin \text{TIME}(f(\lfloor n/2 \rfloor))$.

Proof. Suppose M_{H_f} decides H_f in time $f(\lfloor n/2 \rfloor)$. Let D_f be a diagonalizing machine that computes:

$D_f(\langle M \rangle) : \text{if } M_{H_f}(\langle M, M \rangle) = \text{“yes”} \text{ then “no” else “yes”}.$

This machine on input $\langle M \rangle$ runs in the same time as M_{H_f} on input $\langle M, M \rangle$, that is, in time $f(\lfloor 2n+1/2 \rfloor) = f(n)$.

Does D_f accept its own description? Suppose $D_f(\langle D_f \rangle) = \text{“yes”}$. By our definition of D_f this is done in at most $f(n)$ steps. This means $M_{H_f}(\langle D_f, D_f \rangle) = \text{“no”}$, which means $\langle D_f, D_f \rangle \notin H_f$. This means D_f on input D_f did not accept in $f(n)$ steps, contradiction our starting assumption. Starting with $D_f(\langle D_f \rangle) = \text{“no”}$ we can follow a similar chain of reasoning to get a contradiction.

Putting it all together

- Using the last two lemmas together one can show:
The Time Hierarchy Theorem. If $f(n) \geq n$ is a proper complexity function, then the class $\text{TIME}(f(n))$ is strictly contained in $\text{TIME}(f(2n+1)^3)$.
- This can be improved to $\text{TIME}(f(n)\log^2 f(n))$.

Corollary. P is a proper subset of EXP.

- A similar technique as above can be used to show:
The Space Hierarchy Theorem. If $f(n)$ is a proper function, then $\text{SPACE}(f(n))$ is a proper subset of $\text{SPACE}(f(n)\log f(n))$.

Relationships Between Space and Time

- The following theorem collects together a lot of what we know about the relationships between time and space classes:

Theorem. Suppose $f(n)$ is a proper complexity function. Then:

- a) $\text{SPACE}(f(n)) \subseteq \text{NSPACE}(f(n))$ and $\text{TIME}(f(n)) \subseteq \text{NTIME}(f(n))$.
- b) $\text{NTIME}(f(n)) \subseteq \text{SPACE}(f(n))$.
- c) $\text{NSPACE}(f(n)) \subseteq \text{TIME}(k^{\log n} + f(n))$

Proof. (a) is trivial. To see (b) recall our machine to simulate a nondeterministic machine by a deterministic one, many lectures back could simulate up to $f(|x|)$ steps using the exact same space as the nondeterministic machine except for one auxiliary tape that stores only string up to length $f(|x|)$ coding the nondeterministic choices. We will prove (c) on the next slide.

More on Relationships Between Space and Time

For (c), let L be a language in $\text{NSPACE}(f(n))$ and let M decide it. We assume the input tape is read only and we can ignore the output tape. Therefore a configuration of a k -tape machine looks like $(q, i, w_2, u_2, \dots, w_k, u_k)$. Notice this input tape is replaced with an index i of the tape square we are reading. There are a total of at most

$$|K| \cdot (n+1) \cdot |\Sigma|^{(2k-2)f(n)}$$

configurations. i.e, $c^{\log n + f(n)}$ configurations for some c depending only on M . Given this space of configurations define a graph where we have an edge between two configurations C and C' if there is a one step transition from C to C' according to M . So determining if x is in L is equivalent to checking if an accepting halt configuration is reachable from the start configuration of M on x . Since the reachability algorithm we had before is quadratic in the size of the graph, we can determine this in time $O((c^{\log n + f(n)})^2) = O(k^{\log n + f(n)})$ where $k=c^2$.

Linear speed up then gives the result.

Corollary. $L \subseteq NL \subseteq P \subseteq NP \subseteq PSPACE$.