

# More Turing Machines

CS254

Chris Pollett

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# Outline

- Diagrams, examples, languages
- Recursive, RE, Functions
- Multi-Tape Turing Machines
- Time and Space classes
- Simulations

# A Simple Turing Machine

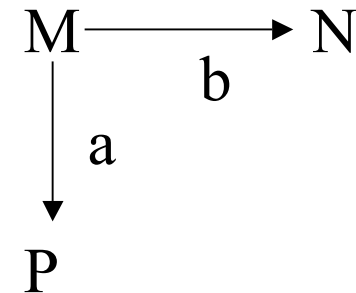
- The transition function is the most important part of a TM's description.
- We will sometimes use a graphical notation to describe TM's and in particular this function.
- Given  $a$  in  $\Sigma \cup \{L, R\} - \{\#\}$ , define a machine  $M_a = \{\{s, h\}, \Sigma, \partial, s\}$ , where for each  $b$  in  $\Sigma - \{\#\}$ ,  $\partial(s, b) = (h, a)$ .  $\partial(s, \#) = R$ .
- That is, if  $a$  is a symbol, the only thing  $M_a$  does is writes that symbol; if  $a$  is L or R then the only thing  $M_a$  does is either move left or right.

# Building Bigger TMs

- Given three TMs with a common alphabet:  $M$ ,  $N$ ,  $P$ , we can build a new machine  $M'$  which operates as follows:

- Start in the initial state of  $M$ ; operate as  $M$  until  $M$  would halt, then
- if the currently scanned symbol is an  $a$ , start  $N$
- if the currently scanned symbol is an  $b$ , start  $P$ .
- halt otherwise.

- Diagrammatically we write:



- As an exercise you should work out what  $M'$ 's transition function would look like.

# More on Diagrams

- Similar to the if-else type diagram of the last slide we can have diagrams like:

$M \dashrightarrow N$

Notice there is no label on the arrow. This means that if machine  $M$  is about to transition to its halt state  $h$  we instead have it transition to the start state of  $N$ .

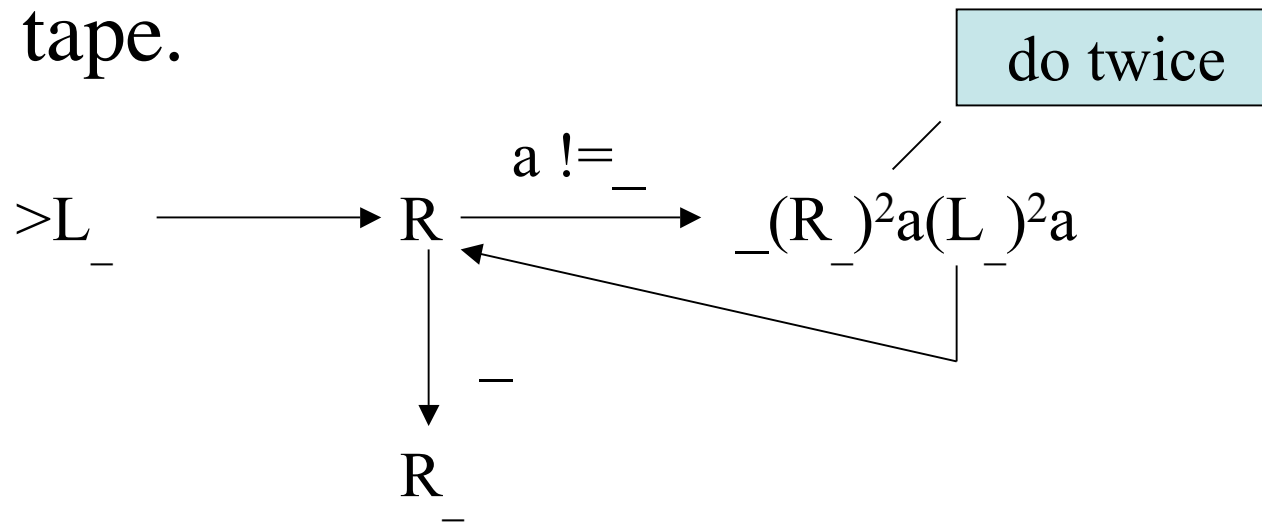
- We can also generalize the two branch construction of the previous slide to any fixed finite number of branches.

# Examples

- We sometimes abbreviate  $M_R$  as  $R$  and  $M_a$  as  $a$ . We might also make abbreviations like  $Ra$  for the machine which does  $M_R$  then reading any symbol write an  $a$ . Similarly, we might have  $RR$  or  $La$ .
- Let  $\Sigma - a$  denote all the symbols in  $\Sigma$  except  $a$ .
- Here is a machine  $R_{\Sigma - a}$  that scans right to the first space  $\triangleright R_{\Sigma - a} \triangleright ! \_ -$
- Here is a machine  $L_{\Sigma - a}$  that scans left to the first space  $\triangleright L_{\Sigma - a} \triangleright ! \_ -$

# More Examples

- Here is a machine which when started with a string  $\_w$  on the tape halts with  $\_w\_w$  on the tape.



# Computing with Turing Machines

- A **configuration of M** is a pair  $(q, \#w\underline{a}v)$  where  $q$  is a state of the TM,  $\#w$  is the string to the left of the tape head,  $\underline{a}$  is the current symbol being read, and  $v$  is the tape square to the right of the head that are either in the input or have been seen so far during the computation.
- The initial configuration of  $M$  is  $(s, \underline{\#x})$ .
- A **computation** of  $M$  is a sequence of configurations of  $M$   
 $(s, \underline{\#x}) :- (q_1, \underline{w_1}) :- \dots :- (q_m, \underline{w_m})$   
such that each configuration follows from the previous according to  $M$ 's  $\delta$ . Read  $:-$  as *yields*.
- A computation halts if either the state yes or no is reached.
- A machine  $M$  **accepts a language**  $L$  if it stops with state yes when  $x$  is in the language and runs forever otherwise.



# Recursive and Recursively Enumerable

- A language  $L$  is said to be **recursively enumerable** if it is accepted by some Turing Machine
- A language  $L$  is said to be **recursive** if there is a Turing machine  $M$  which run on  $x$  that is in  $L$ ,  $M$  halts in the yes state; and when run on an  $x$  not in  $L$ ,  $M$  halts in the no state.

**Proposition** If  $L$  is recursive then it is recursively enumerable.

**Proof.** Suppose there is a  $M$  which decides  $L$ . We can make an  $M'$  which accept  $L$  as follows:  $M'$  behaves the same as  $M$  except that whenever  $M$  is about to halt and enter a “no” state  $M'$  moves right forever and never halts.

# Computing Functions

- Turing machines will be used to model algorithms, so we'll often want to be able to compute functions.

**Definition.** Let  $f$  be a function from  $(\Sigma - \{\_ \})^*$  to  $\Sigma^*$ . Let  $M$  be a TM with alphabet  $\Sigma$ . We say  $M$  **computes**  $f$  if for any string  $x$  in  $(\Sigma - \{\_ \})^*$ ,  $M$  on input  $x$  (written as  $M(x)$ ) halts with  $f(x)$  written on the tape.

- If  $f$  can be computed by some  $M$  we say  $f$  is a **recursive function** or  $f$  is **computable**.
- Our earlier example shows that the copying map is computable.
- We could code instances of networks as strings, and implement MAX FLOW on a TM using our algorithm from Chapter 1. This would show MAX FLOW is computable.

# k tape machine

- One way you might try to improve the power of a TM is to allow multiple tapes.

**Definition** A k-string TM, where  $k \geq 1$  is an integer, is a quadruple  $M = (K, \Sigma, \delta, s)$  where  $K, \Sigma, s$  are as in the 1-tape case. Now, however, the transition functions is a map

$$\delta: K \times (\Sigma \cup \{\#\})^k \rightarrow (K \cup \{h, \text{yes}, \text{no}\}) \times (\Sigma \cup \{L, R\})^k$$

- Basically the heads on each tape can move independently of each other.
- For example, with a two tape machine an algorithm for palindrome testing is easy.
  - We set up the transition function so it first copies the first tape input to the second tape.
  - Then it rewinds the first tape and leaves the second tape at the end of the input.
  - Then the first tape moves right while the second tape moves left and we compare the two tape symbol by symbol. If they don't match we halt in a no. If the second tape gets back to the # then we accept.

# TIME and SPACE classes.

- We shall use the  $k$ -tape model of TM as our basic model to study time and space complexity.
- Let  $f:\mathbf{N} \rightarrow \mathbf{N}$ . We say that machine  $M$  operates within time  $f(n)$  if for any input string  $x$ , the time required by  $M$  on input  $x$  is at most  $f(|x|)$ . Here  $|x|$  is the length of  $x$  as a string. We can make a similar definition for space.

**Defn.** We say that a language  $L$  is in **TIME**( $f(n)$ ) (resp. **SPACE**( $f(n)$ )) if it is decided by some  $k$ -tape TM in time  $f(n)$  (resp. space  $f(n)$ ).

- For example, the algorithm for palindrome in time **TIME**( $3(n+2)$ ).
- You can show for a single tape machine for palindrome you need at least time  $\Omega(n^2)$ .
- How well can a 1-tape machine simulate a  $k$ -tape machine?

# Simulating k-tape by 1-tape

**Thm.** Given any k-tape machine  $M$  that operates within time  $f(n)$ , we can construct a 1-tape machine  $M'$  operating within time  $O((f(n))^2)$ .

**Proof.** Let  $M=(K,\Sigma,\partial,s)$  be a k tape machine.

- The idea is  $M'$  alphabet,  $\Sigma'$ , is going to be expanded to include symbol  $\#'$  to denote the last used square of a tape. And we are going to add to  $\Sigma'$  a symbol  $\underline{b}$  for each symbol  $b$  in  $\Sigma$ .
- A configuration of  $M$  can now be written as:  
( $q, \#w_1\underline{a_1}v_1\#w_2\underline{a_2}v_2\#\dots\#w_k\underline{a_k}v_k\#'$ )
- So except for the state which we can keep track of in  $K'$  the rest of the state is a string over  $\Sigma'$ .
- We will use new states  $K'$  to keep track of the state of  $M$  during a simulation step.
- To simulate  $M$ , we first convert the input into the initial configuration of  $M$  viewed as a string.
- Then to simulate a step we scan left to right the current configuration string, noting what symbol is being read by each tape in our finite control.
- Next we rewind the tape and we then do passes again to update each tapes configuration.
- In the worst case we need to expand the number of tape square of each tape by 1. So we could need  $(k(f(|x|)+1)+1)$ , passes to simulate 1 step.
- So simulating  $f(|x|)$  steps take at most  $f(|x|)((k(f(|x|)+1)+1)$  times which is  $O((f(n))^2)$ .