Searching for solutions

How do we solve above kinds of problems?

We will use problem to create a search tree. Root of tree is initial state. (vertices of tree called sarch nodes) General strategy at a search node – apply goal test to see if node satisfies goal. If yes done. If no, apply successor function to get all nodes reachable from current node in one step (expanding a node). Add these nodes to a list of nodes we need to consider. Pick some node from this list and repeat.

Strategies for picking which node to expand next.

- Depth First Search (always expand left most node that still can be expanded)
- Breadth first search (Expand root, then expand all children of root until reach goal.)

Uninformed Search Strategies

(don't have any way of telling if getting close to a solution)

Time Complexity of Breadth First Search

Suppose each node expands into b children Then to search for a goal of depth d takes time proportional to $1 + b + b^2 + ... + b^d = b^{d+1} - 1 = O(b^d)$ Space complexity is also $O(b^d)$

Depth First Search – Always expand the deepest node that can be expanded (if tie choose left most node)

Time complexity of DFS

If tree has a solution of depth m and this bounds length of any path, let's say branching factor b. Then time takes is $O(b^m)$

Only need to remember path to use algorithm so space complexity is O(b*m)

Problem can get stuck on infinite branches and never find a solution.

Depth limited search upto L search

does depth first search to some fixed depth L
(i.e. not allowed to expand node to depth >= L)
Problem might never find solution because solution has depth > L

Iterative deepening search

Do DLS(0) DLS(1) DLS(2) ... Until find a solution Space Complexity O(bm) Time Complexity O(b^m)