

Texture Mapping, Bump Mapping, OpenGL

CS116B

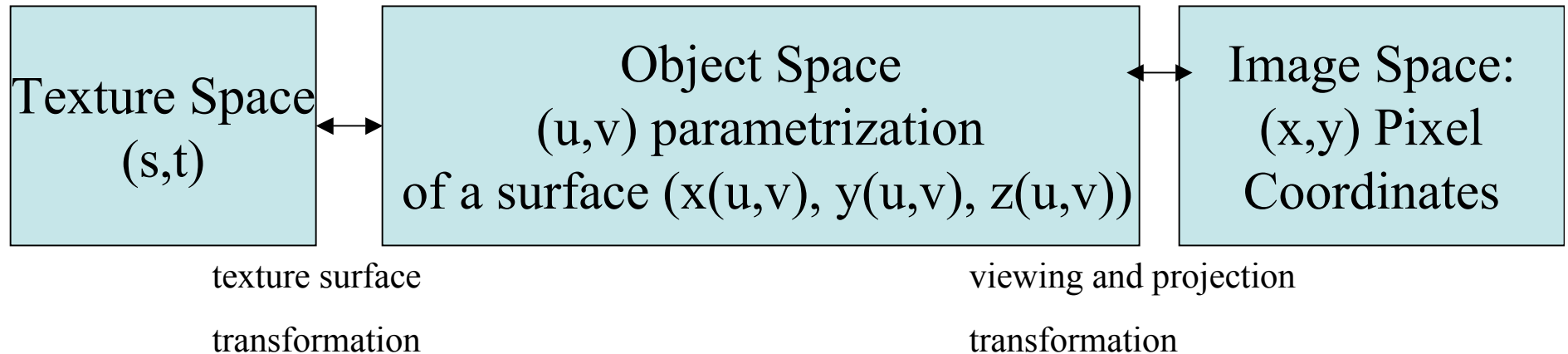
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Outline

- Surface Texture Mapping
- Texture Reduction Patterns
- Procedural Texturing Methods
- Bump Mapping
- Frame Mapping
- OpenGL

Surface Texture Mapping



- Typically, the texture space and the object space are rectangles so can map using the equations:
$$u(s,t) = a_u*s + b_u*t + c_u$$
$$v(s,t) = a_v*s + b_v*t + c_v.$$
- The object space to image space mapping depends on the surface we are parametrizing. For example, for a cylinder we might use $x=r*\cos u$, $y=r*\sin u$, $z=v$.
- We can map either from texture space to image space (**texture scanning**) by composition or can map reverse direction (**pixel-order scanning**).
- The latter is useful to avoid pixel round off errors.

Volume Texturing

- Similar to surface texturing except now texture is 3D. So given by 3 coordinates (s,t,r).
- Might want to do for cut-away displays, scenes like inside a fish-tank,etc.

Texture Reduction Patterns

- As objects get far away, it doesn't make sense to do lots of calculations to apply a texture to them.
- It also can cause distortion in how the texture looks.
- To avoid this we can create different textures of different levels of detail to use depending on the scale of the object.
- These texture reduction patterns are often called **MIP maps** (multum in parvo).

Procedural Texturing Methods

- Another technique for adding a texture pattern to an object is to use a procedural definition for the textures that are to be applied.
- That is have a little program that calculates something that looks like wood graining, marble, etc.

Bump Mapping

- Texture are not very effective when trying to model rough surfaces such as oranges, strawberries, or raisins.
- The problem is the light intensity given in a texture for such an object does not depend on the light in the scene. But these objects change a lot according to the lighting.
- **Bump mapping** is a technique to make realistic bumpy surfaces that can be used instead.

More Bump Mapping

- Let $\mathbf{P}(u,v)$ be a point on a surface.
- Then $\mathbf{N} = \mathbf{P}_u \times \mathbf{P}_v$ is the normal at (u,v) . Let $\mathbf{n} = \mathbf{N}/|\mathbf{N}|$.
- We can add a bump to the surface using an equation: $\mathbf{P}'(u,v) = \mathbf{P}(u,v) + b(u,v)\mathbf{n}$.
- Here $b(u,v)$ is a bump function.
- Can show the perturbed normal is now approximately:
$$\mathbf{N}' = \mathbf{N} + b_v(\mathbf{P}_u \times \mathbf{n}) + b_u(\mathbf{P}_v \times \mathbf{n})$$
- We now use this normal to do our lighting calculations.

Frame Mapping

- This is an extension to bump mapping.
- We not only perturb the surface normal, we also perturb the local coordinate system at the point.
- To do this we tweak the tangent vector \mathbf{T} and calculate a binormal as $\mathbf{B} = \mathbf{T} \times \mathbf{N}$.
- This is useful in modeling anisotropic surfaces, such as wood grains, cross threading in clothing, and streaks on marbles.